# MicroCART Mini

Contextualization /
Design Check-In

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### **Project Overview**

#### MicroCART: Microprocessor Controlled Aerial Robotics Team

- Design mini quadcopter platform to be used in CPRE 488 and for Controls & Embedded Systems researchers
- Develop mini quadcopter printed circuit board (PCB), containing a Microcontroller, RF,
  - IMU, and Wi-fi chip
- Develop software to stabilize and communicate movements
- Develop base-station to communicate with quadcopter
- Create and improve documentation and video tutorials for future teams



CrazyFlie micro-quadcopter

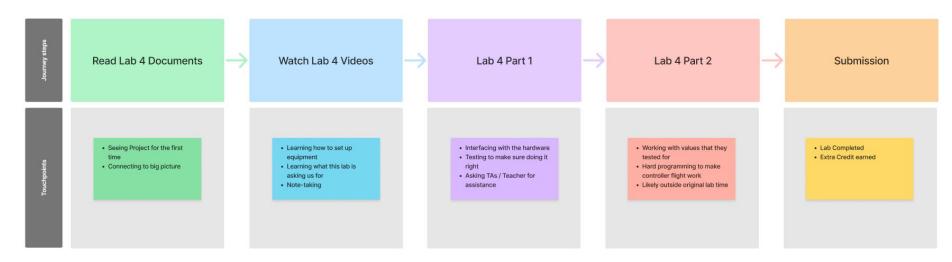
### **Our Goals**

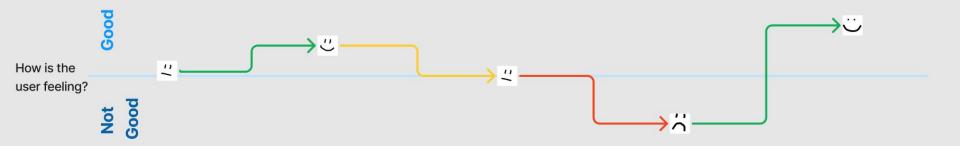
Design/Improve a quadcopter platform integrating both hardware and software to be used for hands-on learning in CPRE 488.

Ensure both remote accessibility and usability for future users through documentation and tutorials



# Journey Map





### Pros/Cons Table

#### **Chosen solutions:**

- Polish current backend
- Implement a Test Stand
   Tracker and connecting
   it to Backend



Polish flag

Solutions	Pros	Cons
Start Fresh	Fix all known problems	More bugs since not user tested     Potentially unable to be completed in time     Takes a long time dedicated solely to this task
GUI instead of Backend code fix	<ul> <li>Quick &amp; easy</li> <li>Leaves project in working state</li> </ul>	Doesn't solve issue itself, only embellishes and potentially even hides the actual issue from future project groups
Polish current Backend	<ul> <li>Makes current project better for users</li> <li>Lets all teammates work on project at once</li> </ul>	Broad in scope     Fixes not synced will cause communication issues
Combine Backend languages	Single navigable document     Able to test and check for changes from one piece of code	Likely to leave project not working or worse off Different coding languages have different advantages for their individuality Let alone fixing existing problems, will likely create more trying to reimplement different file's features. Will have to search through the rest of the code to see where other files were previously connected and adjust them as well.
Implement a Test Stand Tracker and connecting it to Backend component	Inherited template code from past MicroCART team     Better user experience and understanding	<ul> <li>Does not solve all the issues that the backend is having</li> <li>Might cause hardware issues to pop up because it is a student-designed test stand</li> </ul>

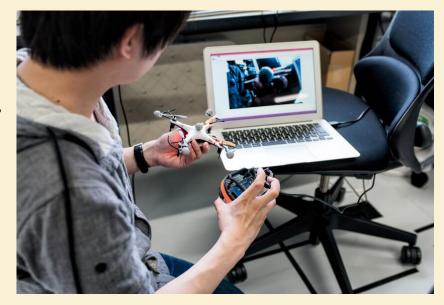
# **Technical Complexity Analysis**

Solutions	Time	Difficulty	Probably Outcome
Start Fresh	5	5	<ul><li>Maybe working</li><li>Many bugs</li></ul>
GUI instead of Backend code fix	1	1	<ul> <li>Working, but still inherently flawed</li> <li>Later project groups may not see what we were looking at</li> </ul>
Polish Current Backend	2	3	<ul><li>Definitely working</li><li>Fixes problems along the way</li></ul>
Combine Backend languages	4	4	<ul> <li>Maybe working</li> <li>Mixed results, not necessarily best</li> <li>Different languages have better results when used for specific purposes</li> </ul>
Implement a Test Stand Tracker and connecting it to Backend component	3	2	<ul> <li>Working</li> <li>Not a cure-all for all of the problems that the backend is having</li> <li>May have other problems later down the line</li> </ul>

### Suitability of Our Design

#### • Human

- Fixing bugs for ease of use
- Reduce difficulties for better user understanding
- Organizing resources for better user experience



## Suitability of Our Design

#### • Economic

- Hardware: self-designed battery holder to improve professionalism
- Software: Updating outdated framework for a more performant system



## Suitability of Our Design

#### • Technical

- Hardware does not change,
   low external complexity
- Frontend and backend communication issues, hard to debug and fix, medium-high internal complexity



### **Conclusions**

- ❖ We have to create the lab materials for next years CPRE 488 class
- Keep documentation and quadcopter statuses up to date to ensure CPRE 488 students have a good experience with their Lab 4
- ❖ Perform extensive testing of software with the drones to find any bugs



#### Works Cited

Jones. "CprE 488 - Embedded Systems Design." Iowa State University,

https://class.ece.iastate.edu/cpre488/schedule.asp